



WOXBOT

# **WOX Bot**

## ***An Open Extensible Robot for Virtual World Simulations***

Marcio Lobo Netto, João Eduardo Kogler Jr.,  
Emílio Del Moral Hernandez, Fabio Roberto Miranda

University of São Paulo - Brazil

# Outline



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- introduction
- previous work
- project overview
- foundations and concepts
- implementation
- conclusion and future work

# Introduction

## *artificial life*



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- simulation of large societies of single beings
  - biologists and physicists
    - study of life origin and evolution
  - mathematicians
    - theoretical aspects (is it possible?)
    - how can programs evolve by themselves?

# Introduction

## *artificial life*



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- simulation of complex evolved creatures (single or multiple bodies)
  - computer graphics community
    - modeling and animation
    - virtual actors
    - individual and population behaviors

# Introduction

## *research goal*



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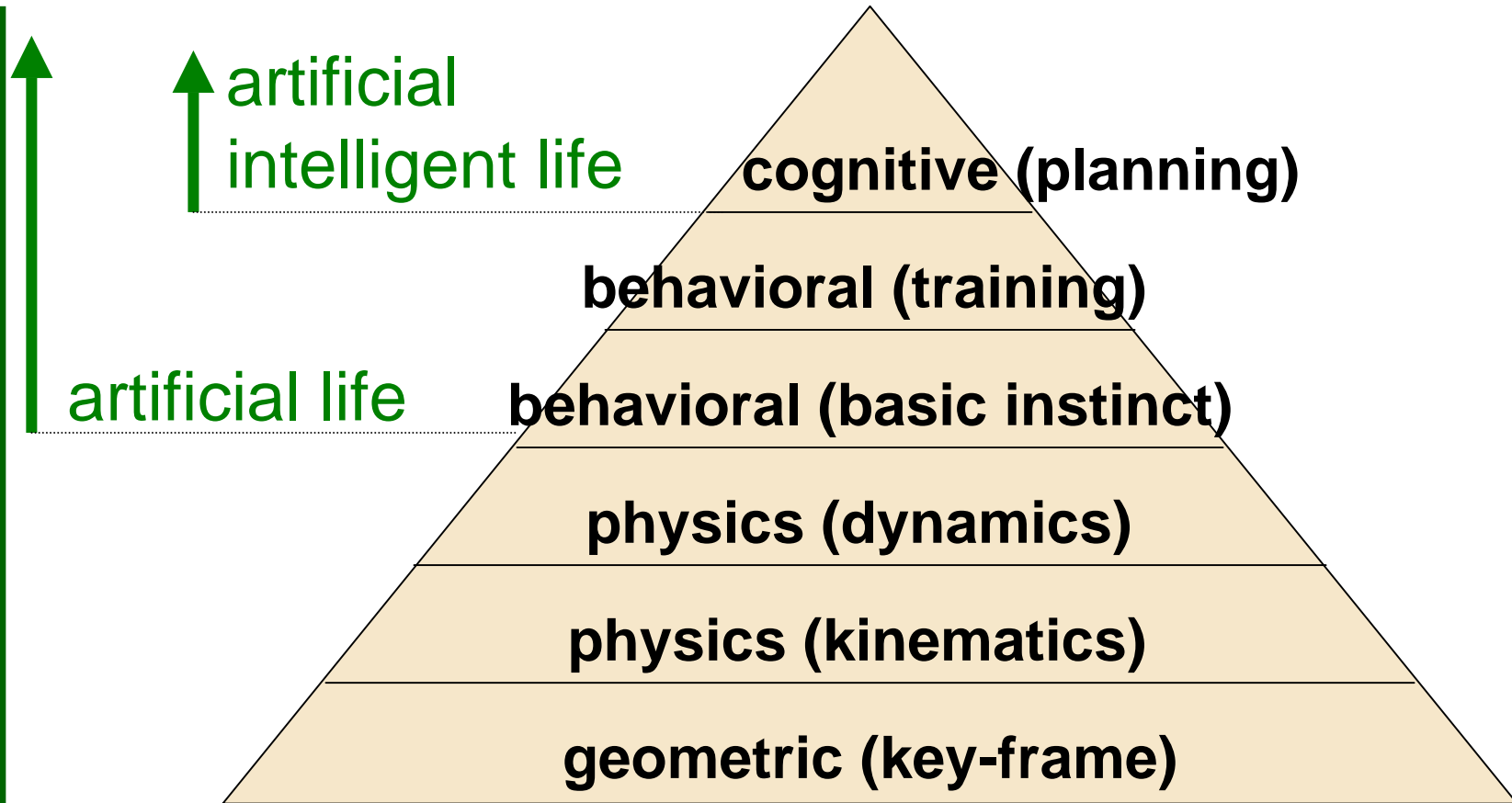
- to study different aspects of artificial life
- character features
  - environment recognition
  - cognition / reasoning / planning / decision making
  - learning abilities
  - action control
  - use of language



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# Previous Work

## *comp. graph. - animation*





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# Previous Work

## *computer graphics*

- Perlin 94-96: behavior animation (Improve)
- Terzopoulos 91-99: behavior and cognition (fishes)
- Talman 80's - 90's: human modeling (human bodies and population)
- Sims 94: evolved competing creatures (nice primitive creatures)

# Project Overview

## *long term goal*



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- to be able to simulate complex virtual worlds with realistic creatures, exhibiting sophisticated behaviors supported by reasoning, learning and cognition



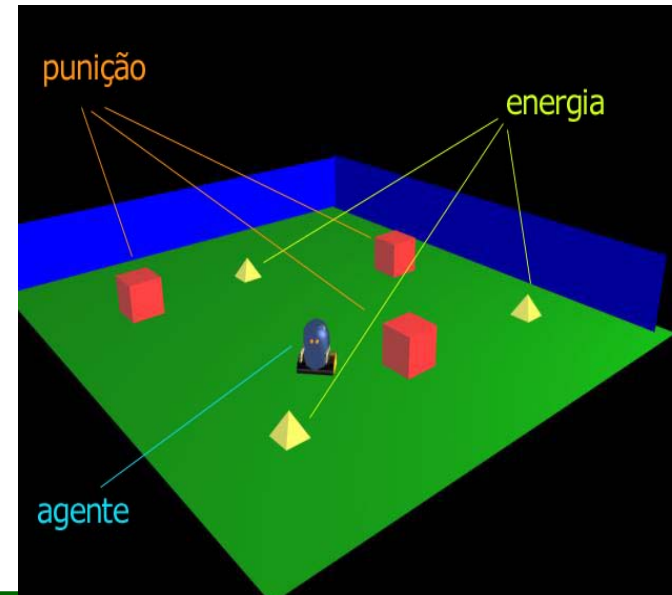
# Project Overview *framework*



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- virtual character
  - WOXBot:  
Wide Open  
Extensible Robot
- virtual environment
  - ARENA: the  
environment inhabited  
by WOXBots



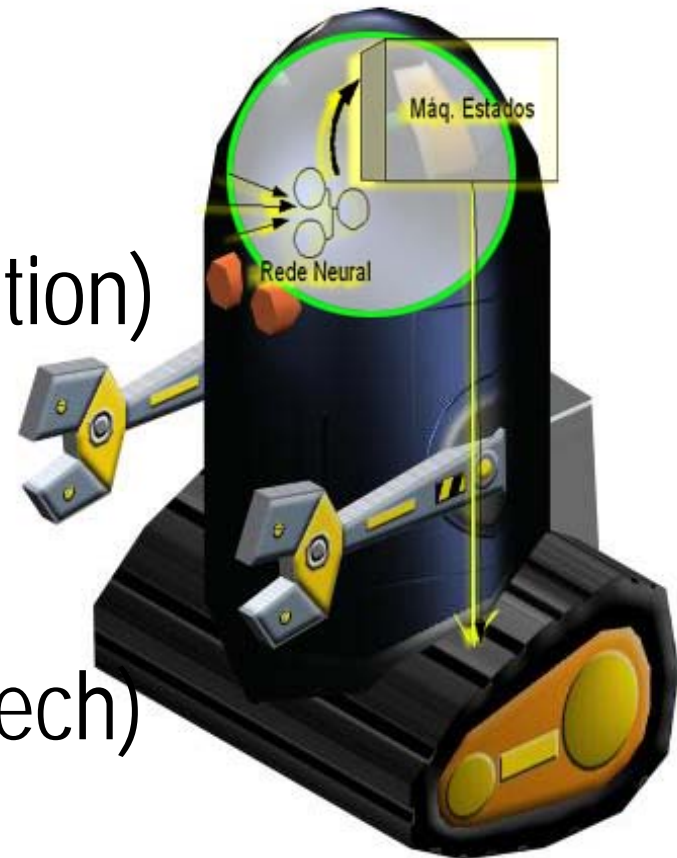


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# Project Overview

## *framework - character*

- actors are one or more robots
- perception (vision, audition)
- features recognition
- decision (behavior)
- action (movement, speech)
- evolution



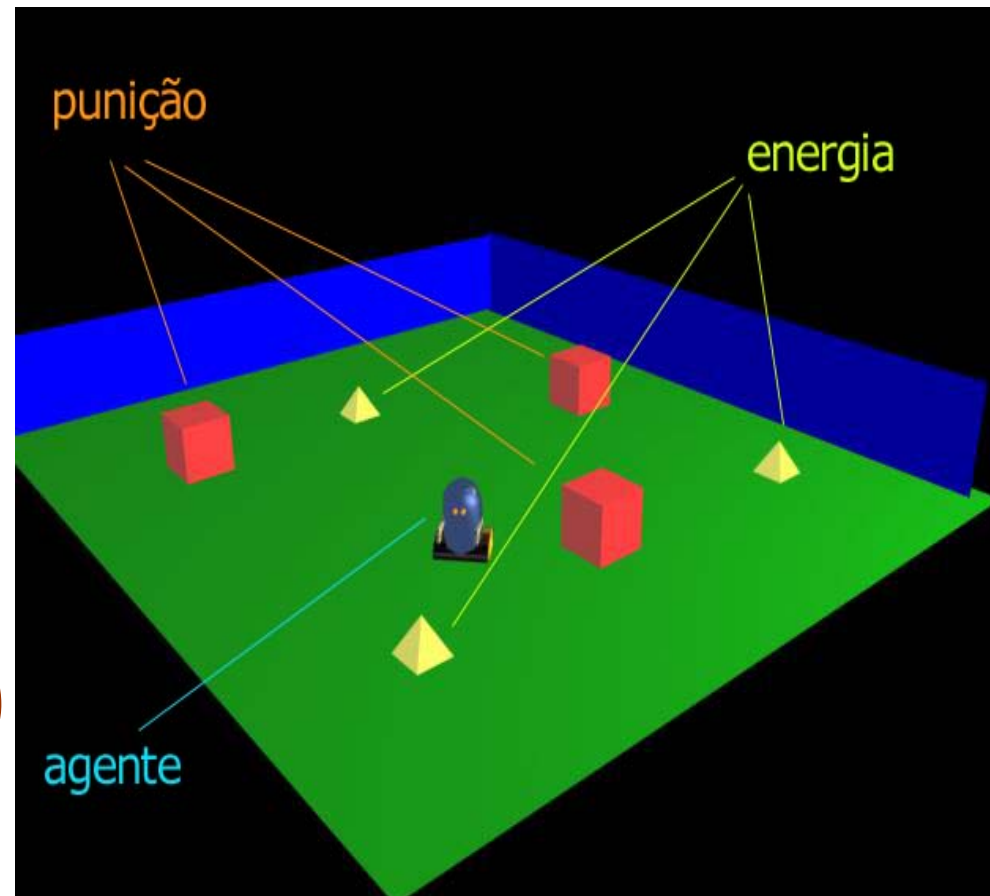
# Project Overview

## *framework - scenario*



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- scene is an area where woxbots live
- scenario for life adaptation
  - rewards
  - traps (punishment)



# Concepts

## *artificial life*



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- cellular automata theory
  - origin and evolution of life
- computer graphics animation
  - natural behavior
- how to achieve it?
  - usage of evolution strategies

# Concepts

## *artificial life*



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- local aspects
  - ability of a character to regulate its own behavior
- global aspects
  - adaptation of a certain specie (trough generations)
  - emerges from the local one

# Concepts evolution & *genetic algorithm*.



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- evolutionary strategies
  - rules of evolution and natural selection
- genetic algorithms
  - codification of beings features into genes
  - generation of new beings by reproduction and mutation



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# Concepts

## *intelligent agents*

- agents
  - to move alone (mobility)
  - to communicate (sociability)
  - to take decisions (intelligence)
- intelligent agents
  - use of knowledge
  - production / update of knowledge

# Concepts

## *intelligent agents*



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- Computational entities that behave with autonomy in order to manipulate the information associated with its knowledge
  - goals
  - motivation (?)
  - reasoning about actions and their consequence



# Implementation *intelligent agents*



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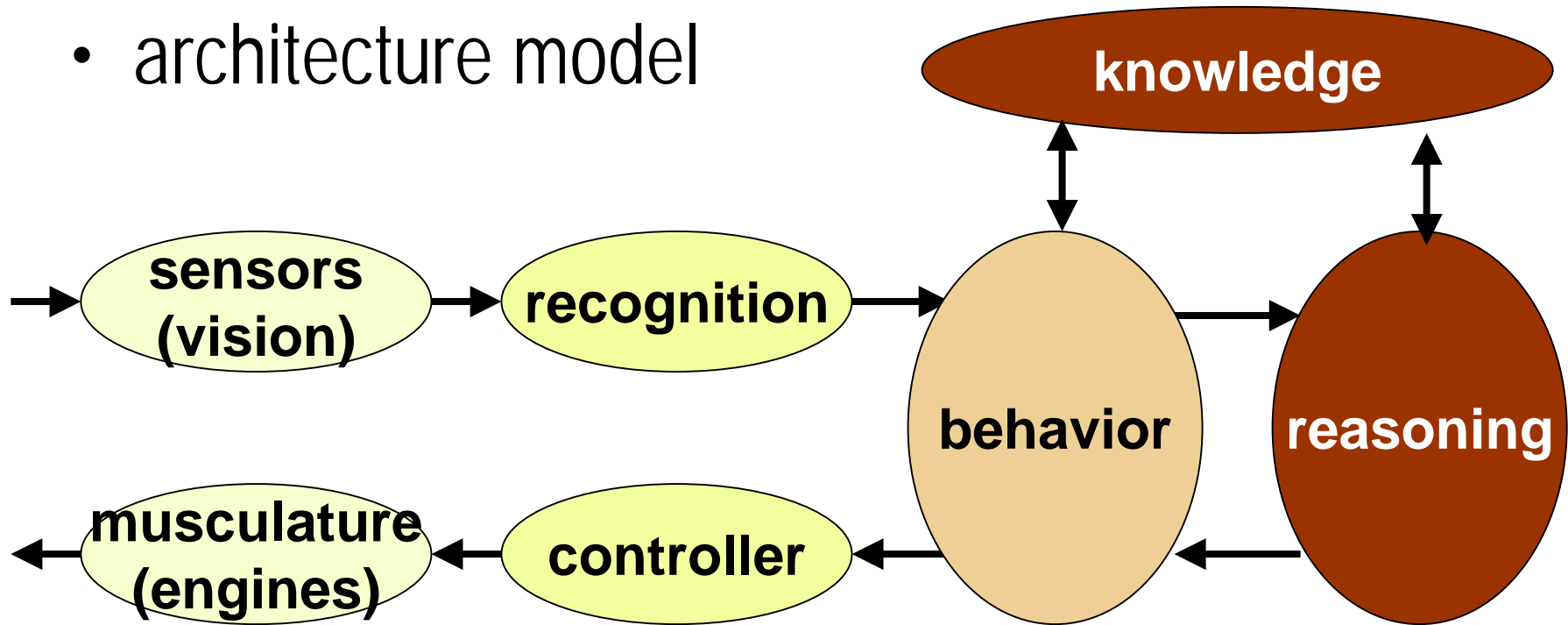
- each module can be
  - pre-specified (hard coded)
    - does not allow adaptations without programmer interference
    - able to be trained or not
  - based on evolution concepts
    - naturally adapted
    - allow improvements to be achieved spontaneously



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# Implementation *intelligent agents*

- architecture model



# Implementation

## *perceptual modules*



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- vision
  - observation of their environment through simulated vision process
    - image generation (computer graphics camera)
    - image interpretation and recognition (neural nets)
  - learning / training
    - neuronal nets
    - identification of objects and other robots

# Implementation

## *perceptual modules*



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- audition (listening)
  - observation of their environment through simulated listening process
    - symbol generation (sound recognition)
    - information interpretation and recognition (neural nets)
  - learning / training
    - neuronal nets
    - identification of objects and other robots



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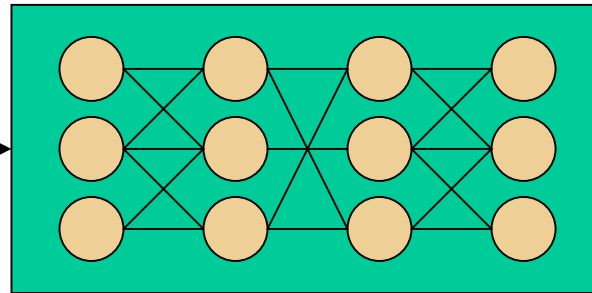
# Implementation

## *learning in perception*

– information recognition from achieved data



**vision image**



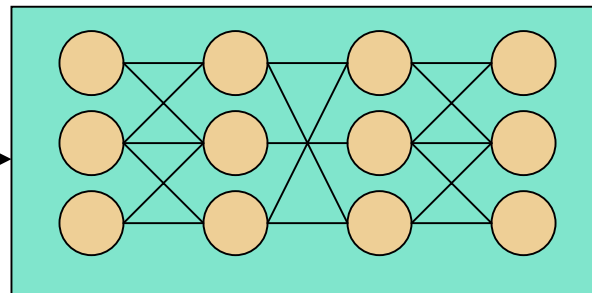
**identification system**

- 0: no object
- 1: obj. @ left
- 2: obj. @ right
- 3: obj. @ center

**coded information**



**audio**



**identification system**

- 0: no sound
- 1: high freq. near
- 2: high freq. far
- 3: low freq. near

**coded information**

# Implementation

## *action and behavior*



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- behavior defined in a state evolved machine
  - trough evolution there is a natural improvement in the state machine
- actions are related to state transitions
- sensor inputs control state transitions
- states represent a memory about the current situation

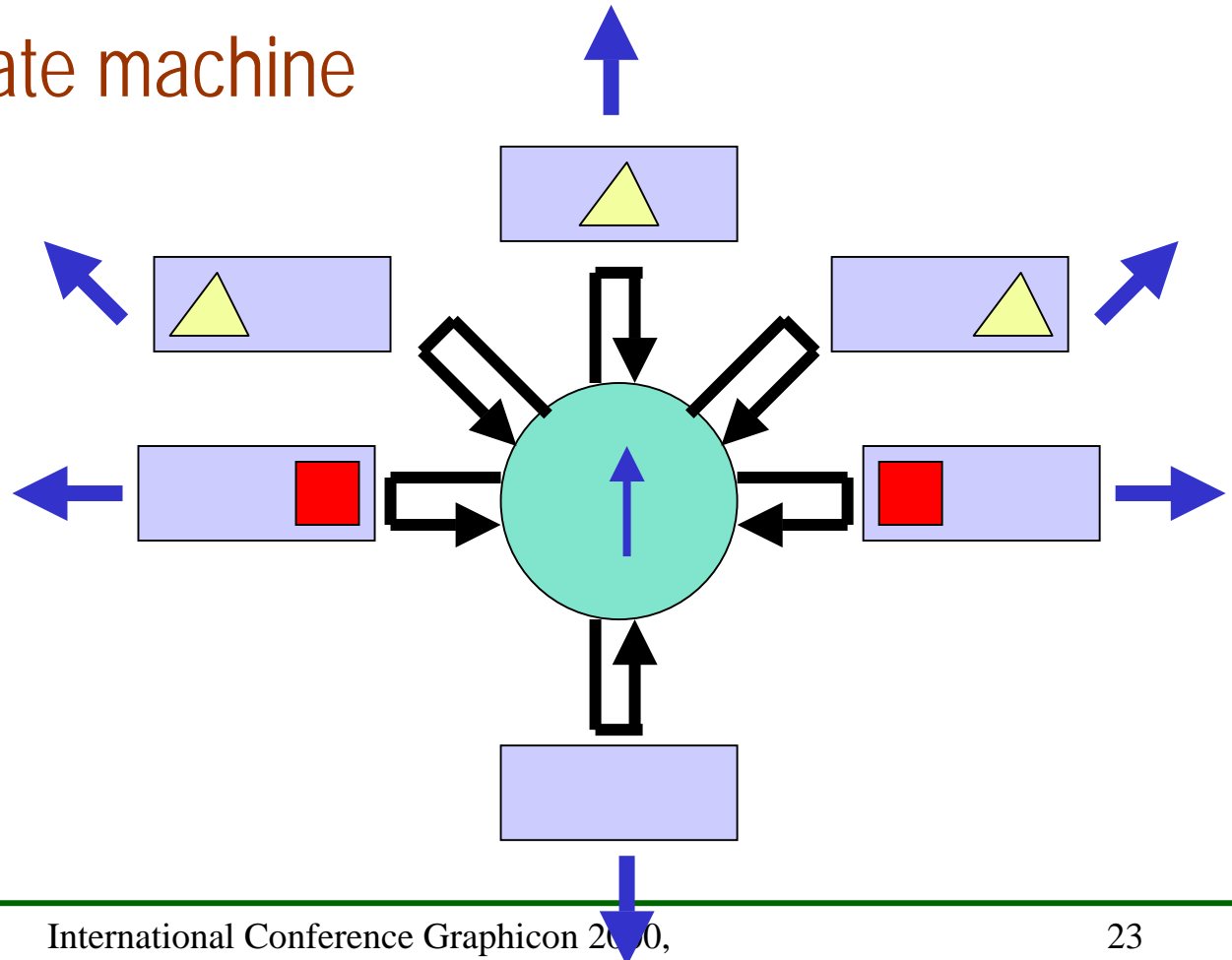


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# Implementation

## *action and behavior*

– single state machine



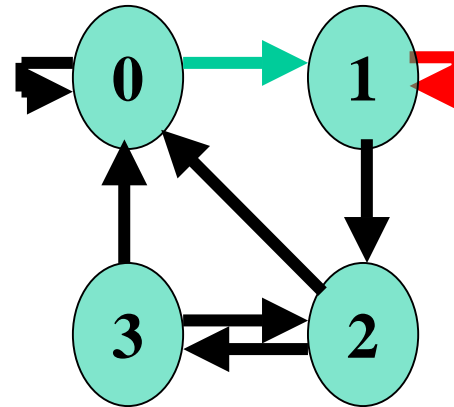
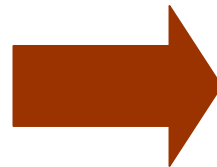
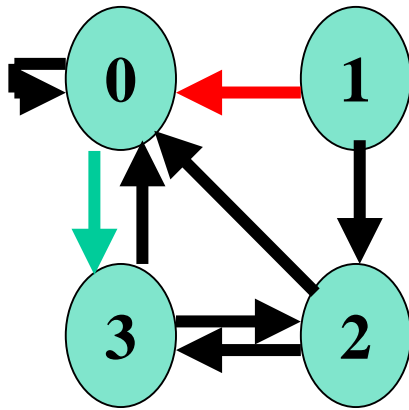


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# Implementation

## *action and behavior*

– behavior state machine (without special meaning)



**states**

- 0 stay
- 1 going ahead
- 2 turning right
- 3 turning left

<u>S</u>	<u>ISA</u>	<u>ISA</u>
0	0 0 X	1 3 Z
1	0 2 Y	1 0 Z

<u>S</u>	<u>ISA</u>	<u>ISA</u>
0	0 0 X	1 1 Z
1	0 2 Y	1 1 Z



# Implementation

## *action and behavior*



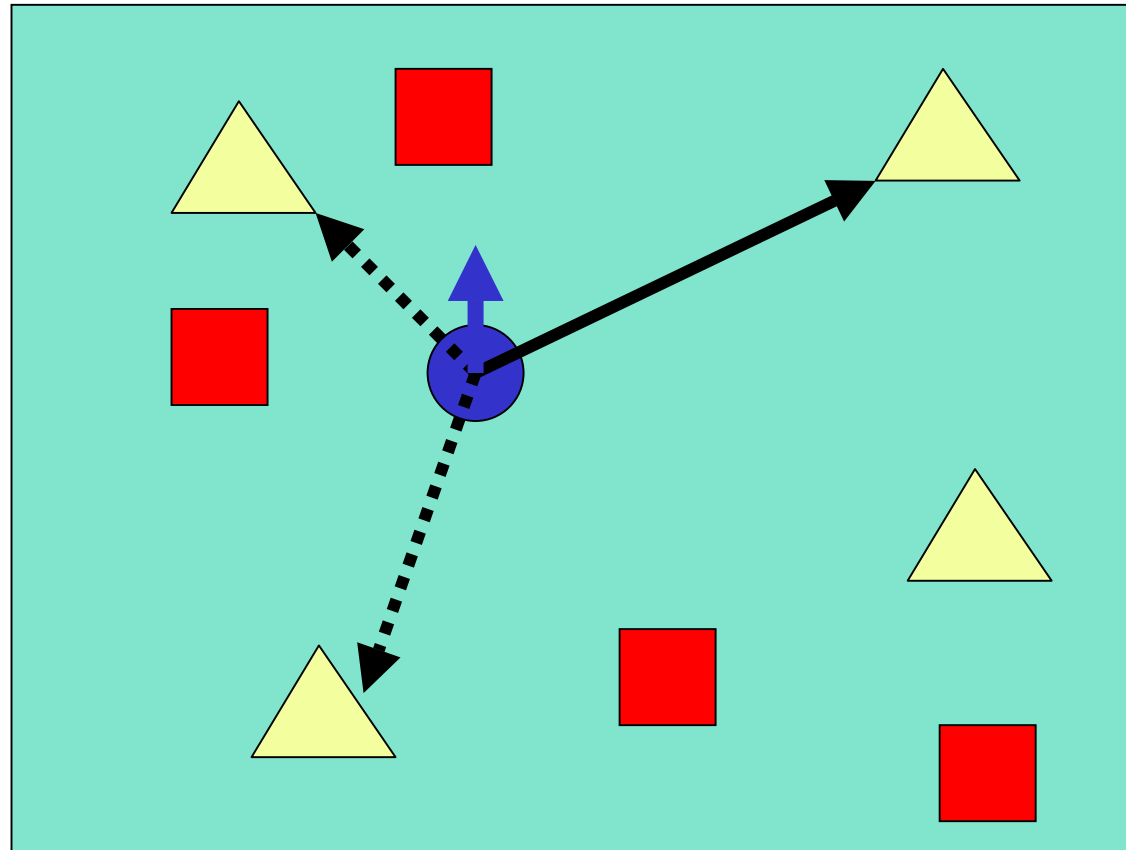
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path planning

tradeoff

gain  $\Leftrightarrow$  lost

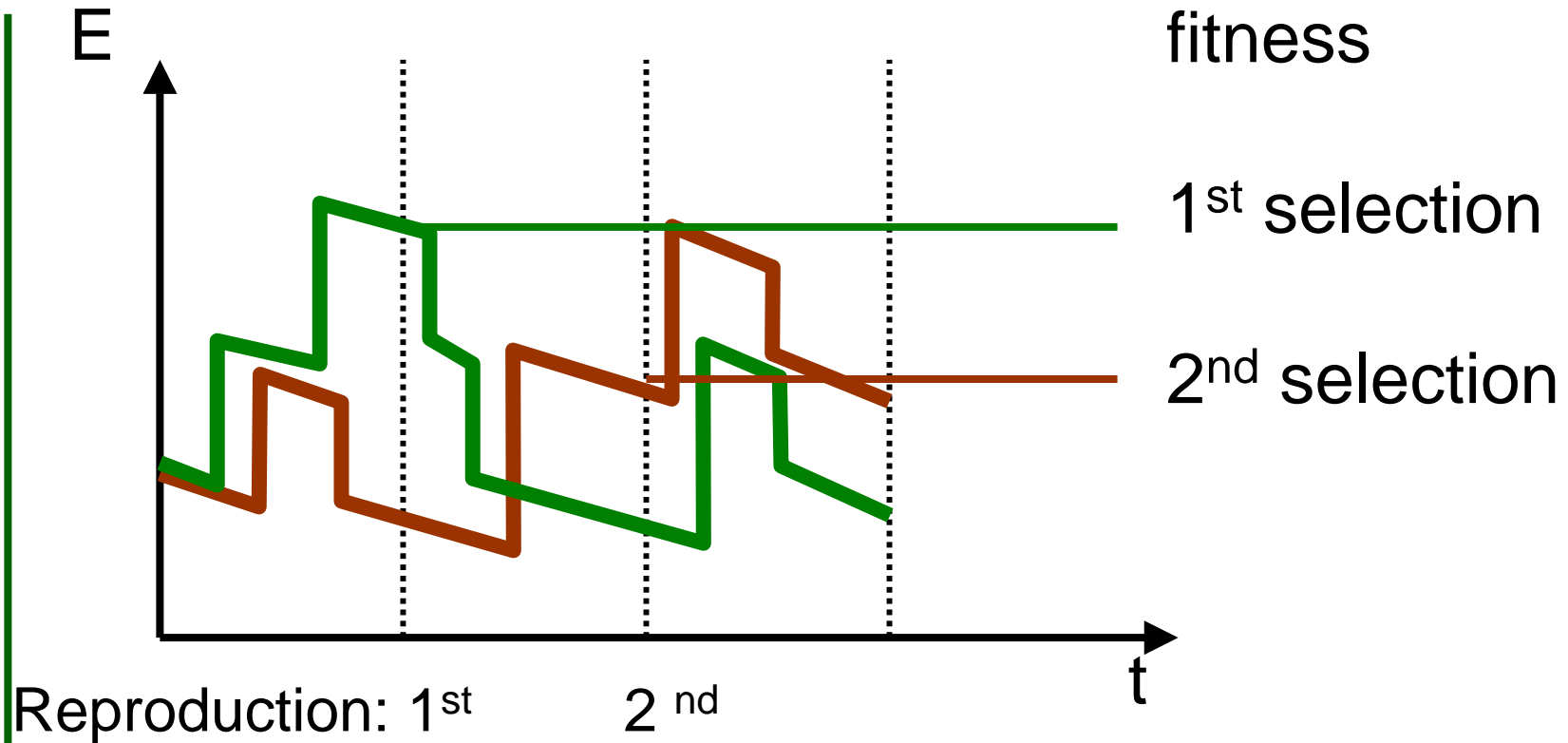
look for pyramids  
avoiding cubes or  
their proximity





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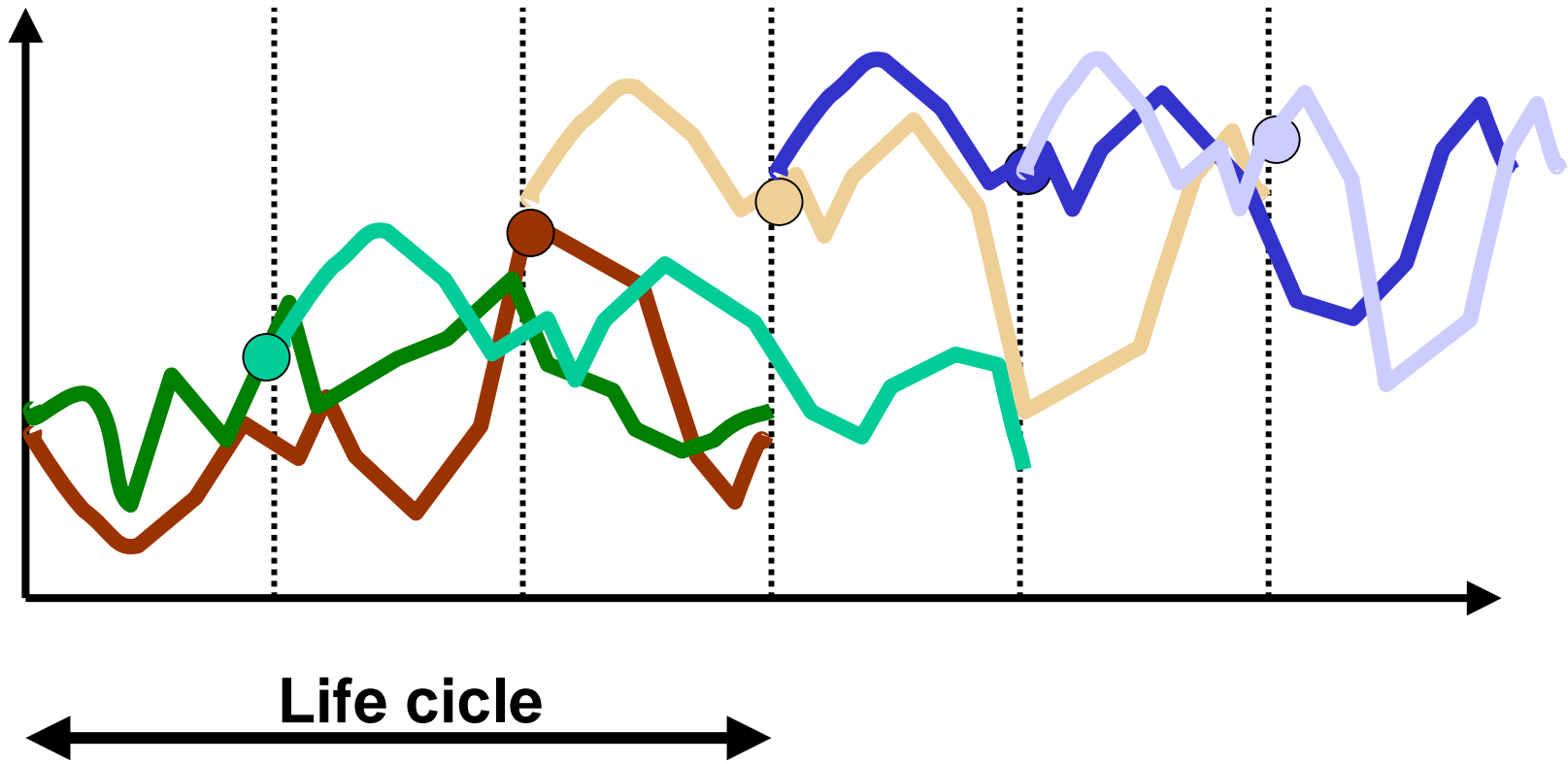
# Implementation *evolution strategies*





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# Implementation *evolution strategies*





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# Implementation

## *evolution strategies*

- life cycle
  - the same for all characters (less interesting)
  - dependent on their energy reserves (more interes.)
- new generation
  - reproduction from best fitted (higher energy)
  - mutation

# Conclusion



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- we presented a new artificial life framework
  - multi-modal perception sensors, with training (learning) capabilities
  - adaptable behavior mechanisms, based on evolutionary concepts
  - until now we have worked with non communicating characters (no language usage)

# Conclusion

## *future work*



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- test and improve communication mechanisms
  - speech and its recognition
  - language development
  - requires improvements in audition simulation
- improvements in state machine evolution
  - allowing an increase in the number of states

# Conclusion

## *future work*



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- incorporate planning
  - knowledge base
  - how to evolve to natural cognition based on evolution ???
  - how to add emotion, and its consequences ???
  - how to incorporate the possibility to choose reproduction partners ???