



# *Orthopaedic Surgery Training on Personal Computer*

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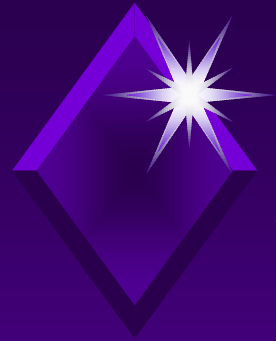
Nanyang Technological University, Singapore

Stanislav Klimenko

Moscow Institute of Physics and Technology

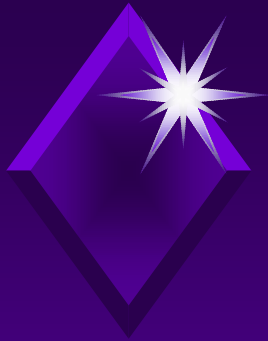
Howe Tet Sen

Singapore General Hospital, Singapore



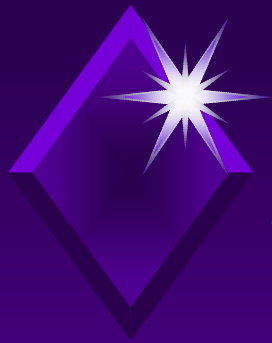
# *Background and Objectives*

- ◆ Singapore General Hospital,  
Department of Orthopaedics
- ◆ Existing training using synthetic bones
- ◆ Aim to virtual training using geometric models of the synthetic bones
- ◆ Further aim to orthopaedic surgery simulation using geometric models of the bones reconstructed from CT data



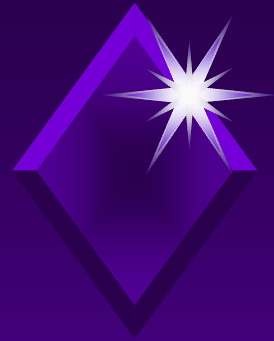
# *System Design*

- ◆ Virtual Bonesetter
- ◆ MS Windows95, Criterion's Renderware
- ◆ Open VR system that includes the following objects:
  - ◆ Fractured bones
  - ◆ Implants
  - ◆ Surgical instruments
- ◆ Extendable set of models



## *Data Source*

- ◆ Fractured bones
  - ◆ Reconstruction from CT data
  - ◆ Fracture modelling
- ◆ Implants and tools
  - ◆ Engineering drawings and data from the medical atlases and booklets
  - ◆ Software modelling and interactive design



# *Plastic Bones*





# *Reconstructed Bones*

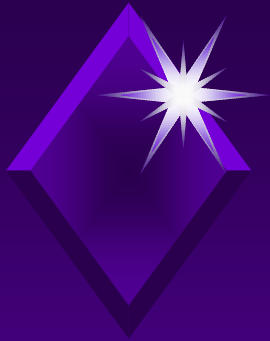


CT

Reconstruction

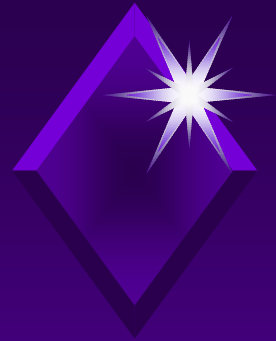
RWX





## *Fractured Bones*

- ◆ Fractures exist in predictable shapes and can simply be modelled
- ◆ Special cases can be reconstructed from CT data



# *Standard Fractures. Example*

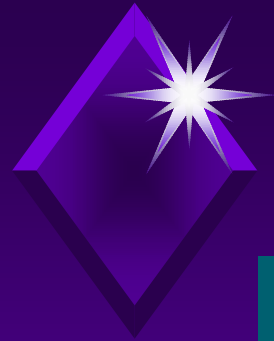
## ◆ Femur

- ◆ Proximal femur - 9 types
- ◆ Femoral shaft - 9 types
- ◆ Distal femur - 9 types

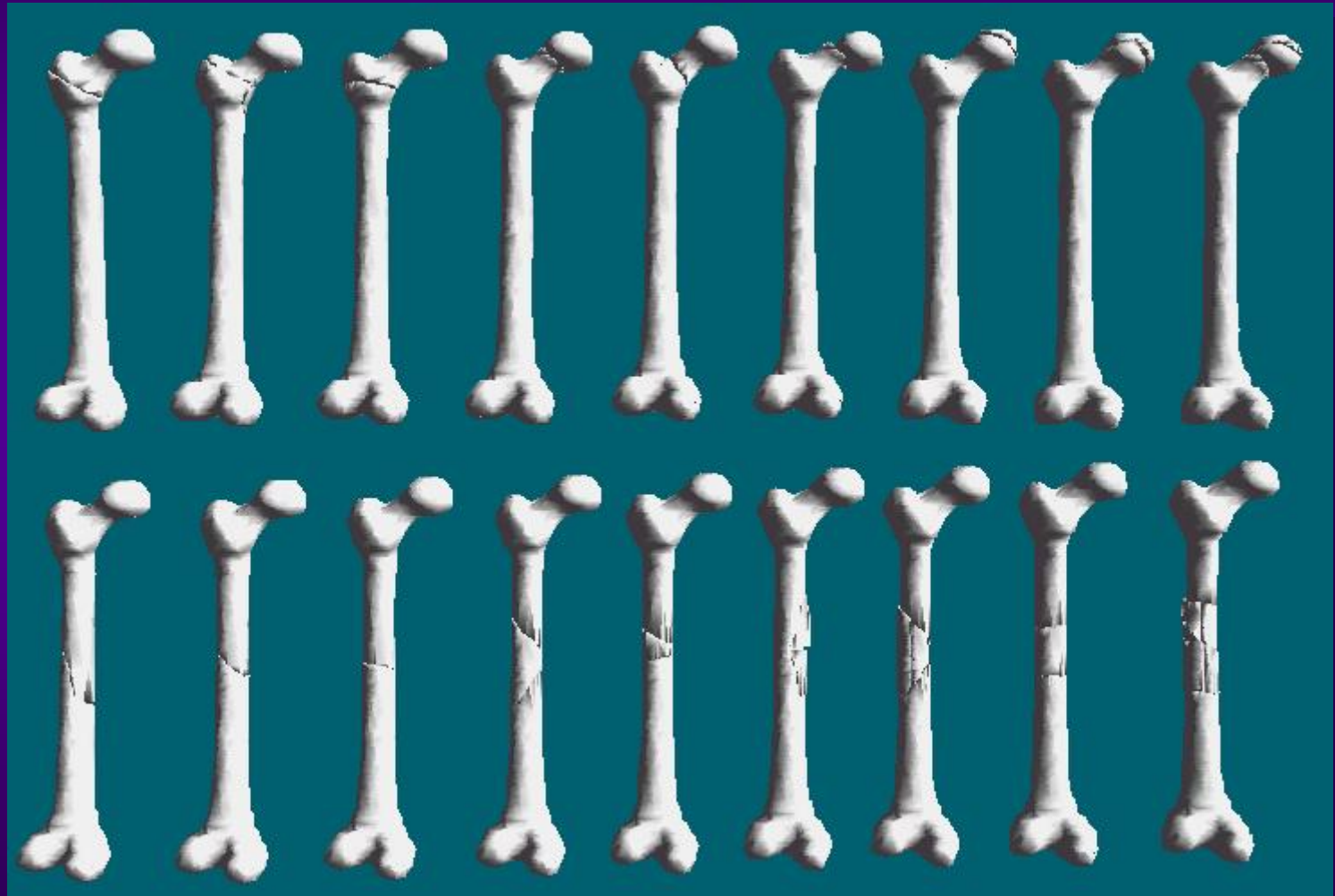
## ◆ Pelvis

- ◆ Stable fractures - 3 types
- ◆ Rotationally unstable fractures - 3 types
- ◆ Totally unstable fractures - 3 types



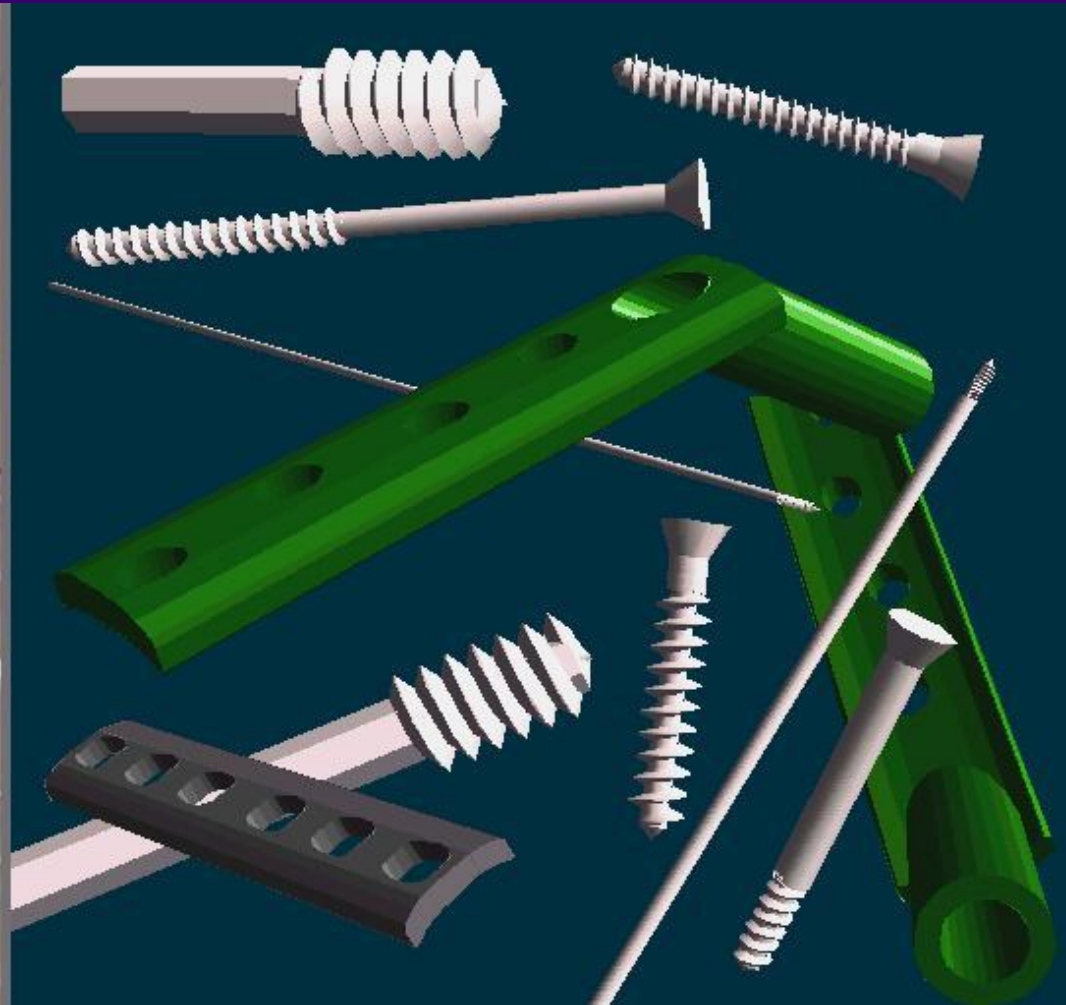


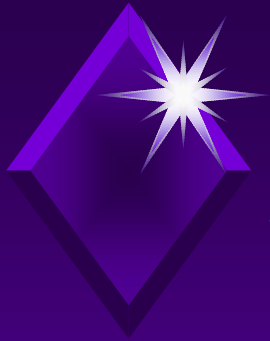
# *Femoral Standard Fractures*





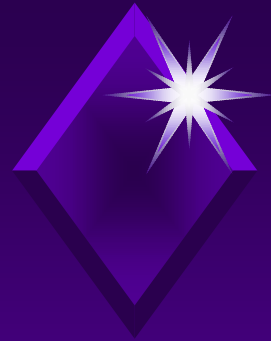
# *Real and Virtual Implants*





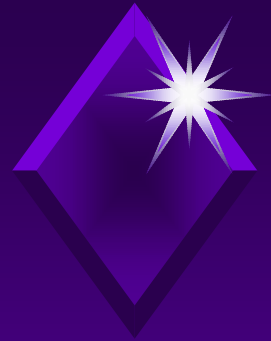
# *Basic Procedures Groups*

- ◆ Application of the instruments and insertion of the implants in place
- ◆ Viewing the objects through “the image intensifier”
- ◆ Rotating and zooming the scene and objects in the scene
- ◆ Walk through the bone canal
- ◆ Reverse process
- ◆ Setting the multiple lights  
(point light sources and spot-lights)
- ◆ Setting the backdrop

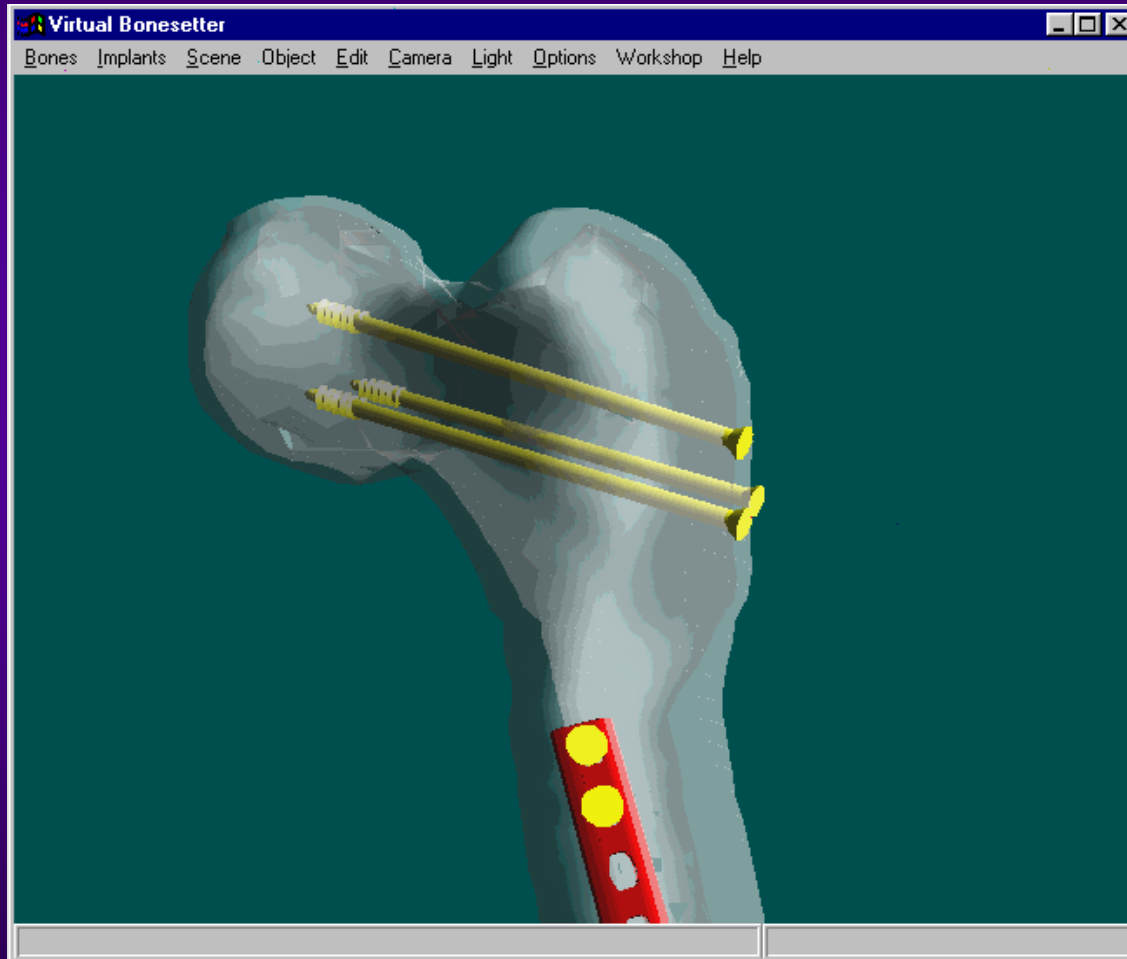


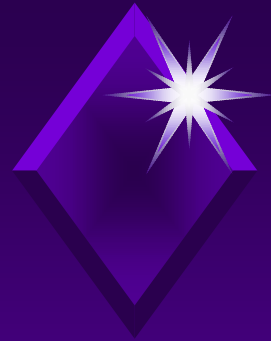
# *Example of Virtual Surgical Procedures*

- ◆ Locate the bone in front of the user
- ◆ Insert threaded guide wire
- ◆ Insert pin
- ◆ Remove threaded guide wire
- ◆ Remove pin
- ◆ Insert multiple guide wires
- ◆ Measure for screw length
- ◆ Insert screw
- ◆ Seat plate
- ◆ Insert nail

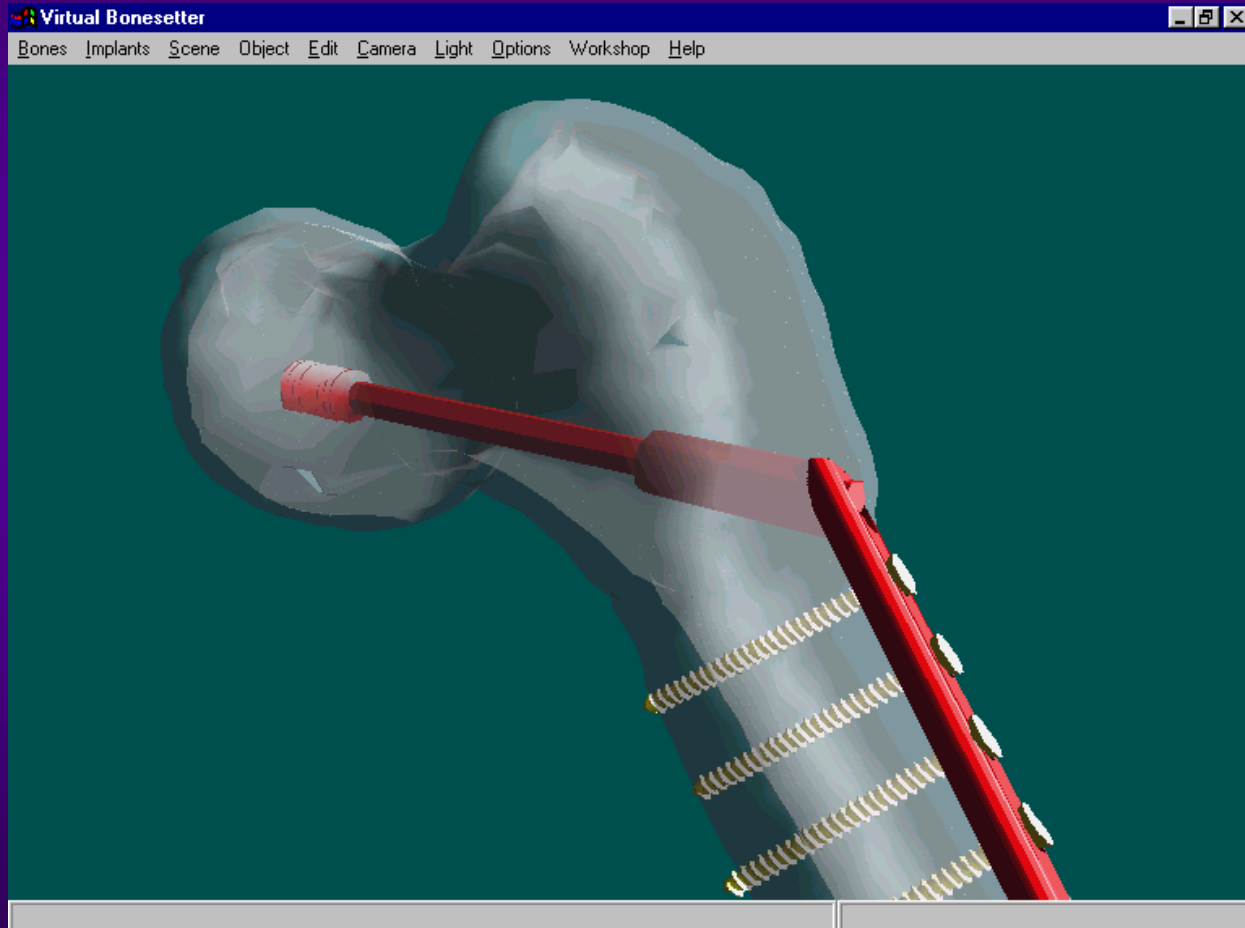


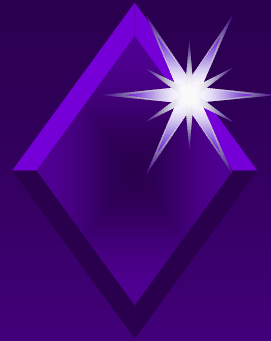
# *Femur Neck Fixation with Cancellous Screws*



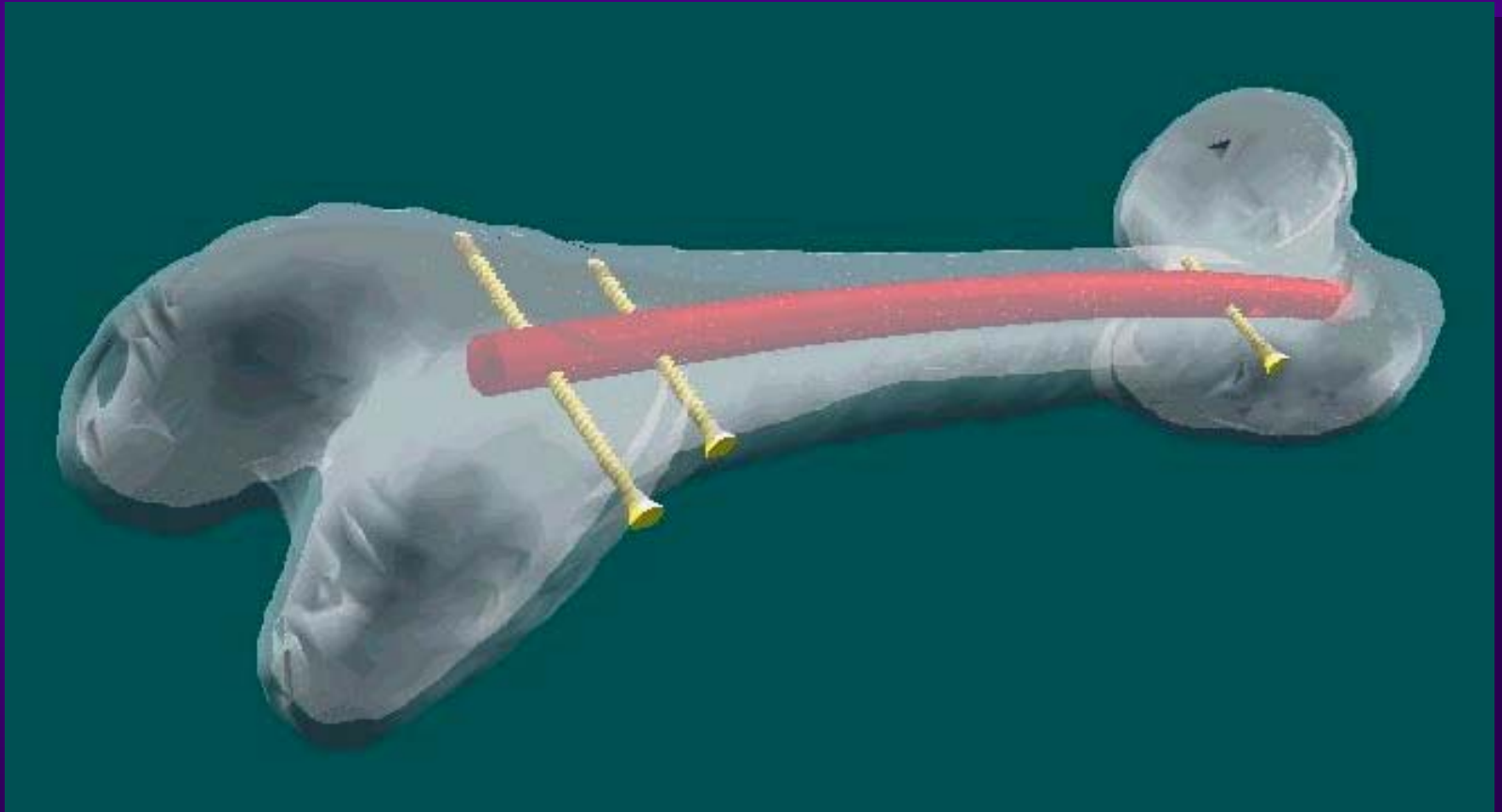


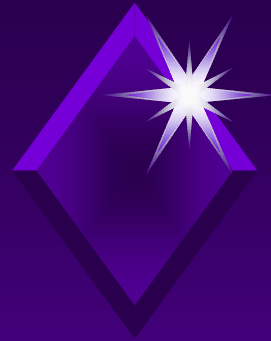
# *Femur Neck Fixation with the Dynamic Hip Screw System*





# *Femur Fixation with an Intra-medullary Nail*

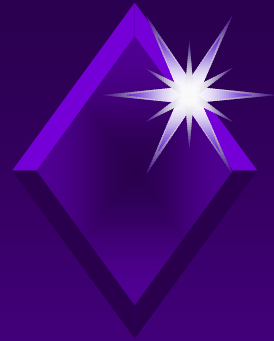




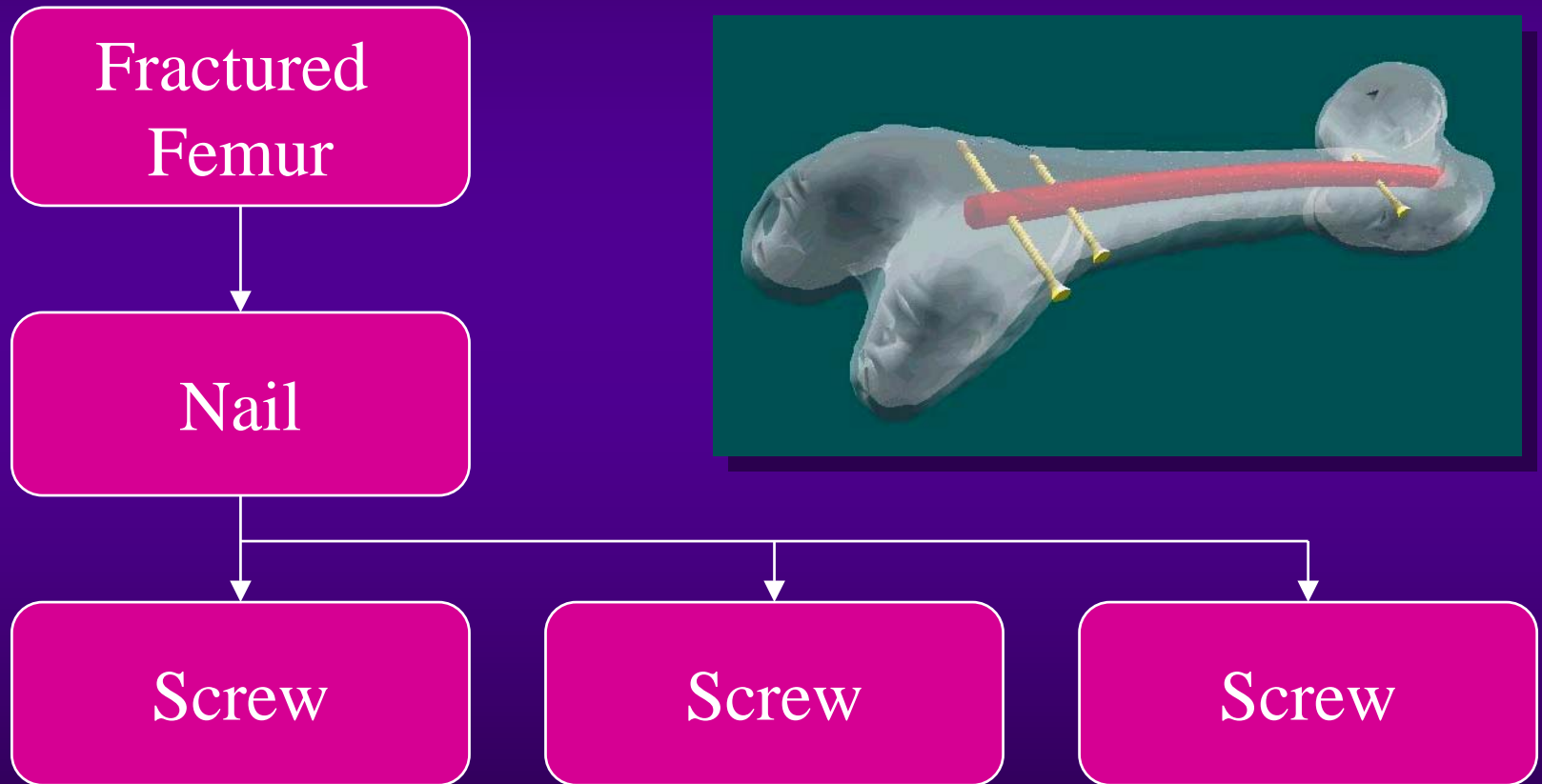
# *Hierarchical Geometric Database*

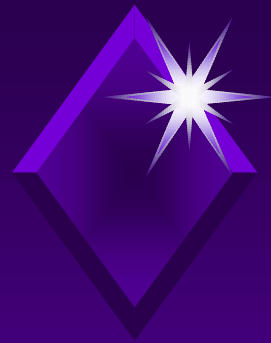
- ◆ Fractured Bone or Implant
  - ◆ Unique ID
  - ◆ Shape - polygonal mesh
  - ◆ Graphics attributes
  - ◆ Extra geometric information used for pseudo-physical collision detection and/or insertion/seating
  - ◆ Parent reference





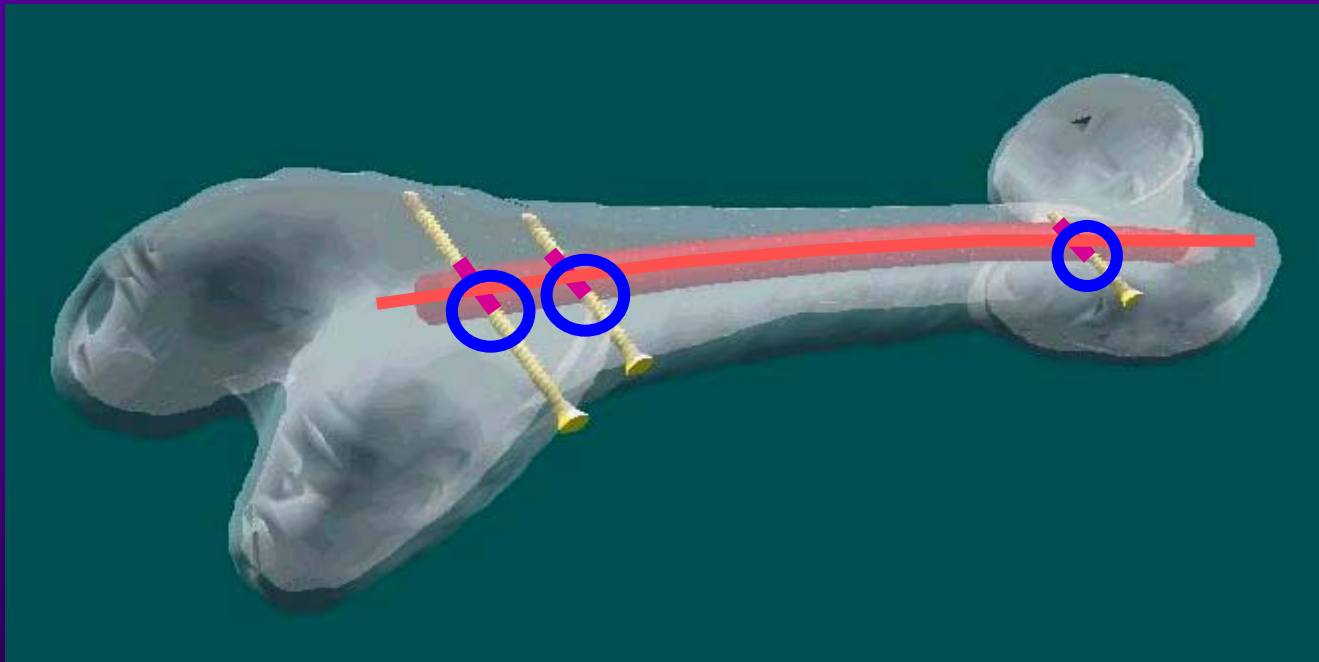
# *Example of Hierarchy*

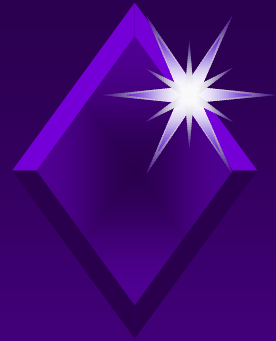




# *Example of Collision Detection*

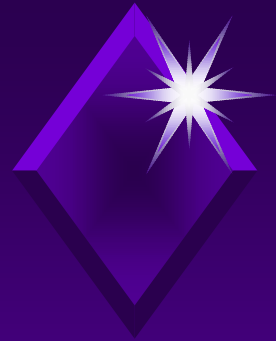
- ◆ Geometric attractive field + axis or centre point(s)





## *Further Development*

- ◆ To extend the library of tools and implants
- ◆ To develop a geometric library of fractured bones
- ◆ To add other specific surgical procedures
- ◆ To incorporate video of actual surgery procedures



## *Conclusion*

- ◆ VB provides the capability to combine 3-D visual imagery of bones with interactivity in support of a realistic surgical simulation.
- ◆ The system could offer many attractive possibilities: lower risk training for students, fewer risks for patients, better scenario-based practice, and minimized cost of training.