

# The Comparison of Illumination Maps Technique in Computer Graphics Software

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# Illumination Maps: VRML



## TESTS

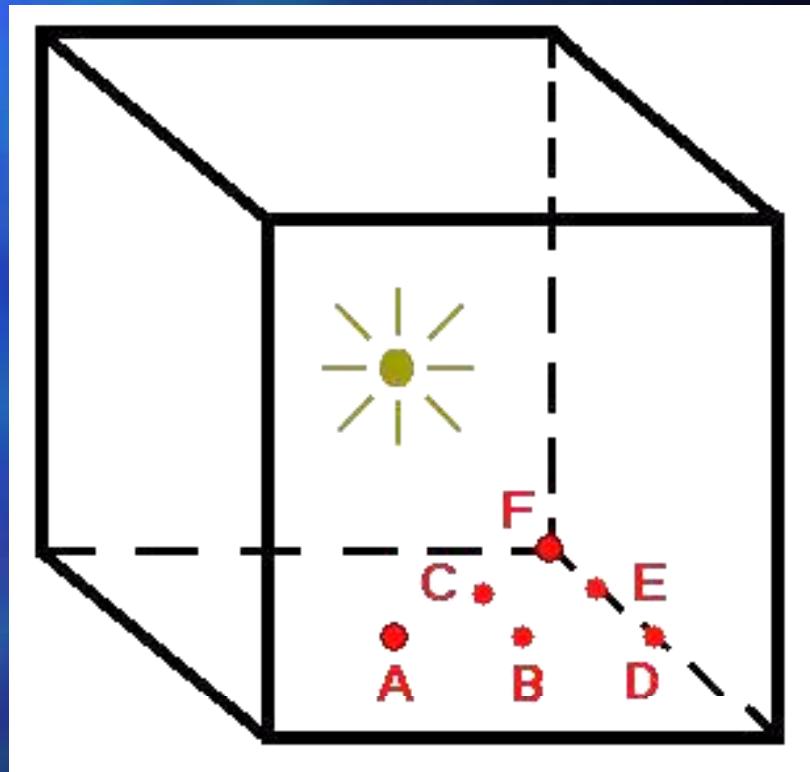
CUBE  
(analytic test)

SPHERE  
(analytic test)

TEST-E  
(practical test)

# CUBE

- $10 \times 10 \times 10$  m
- 50000 cd
- illumination = 2000 lux
- white color
- diffuse reflectivity =  $2/3$

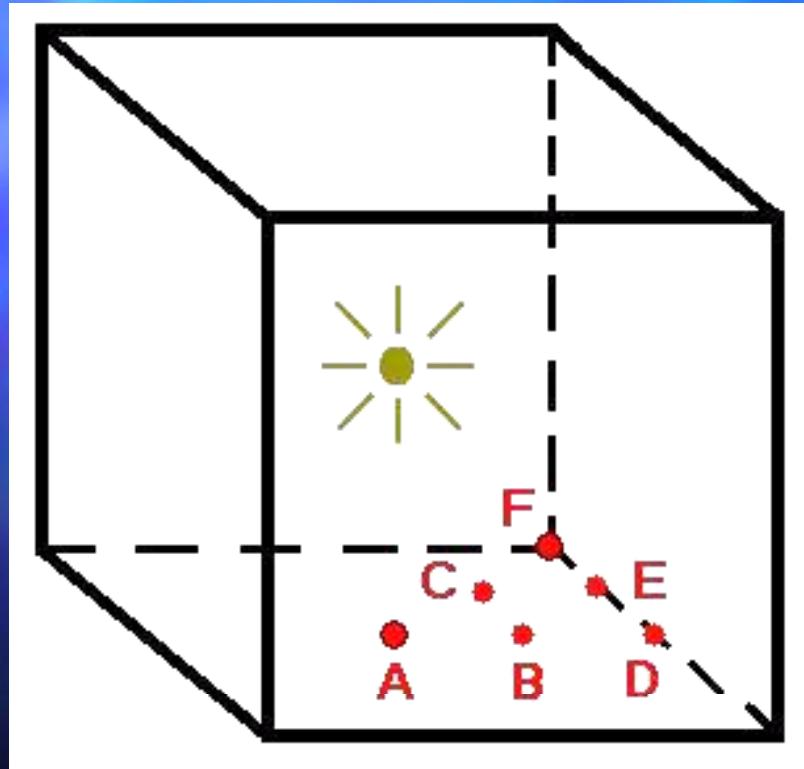


# CUBE: energy transfer equation

$$Illum(p) = \int_{\Omega} \frac{Lum(q) \cdot \cos(\alpha) \cdot \cos(\beta)}{r^2(p, q)} dA(q)$$

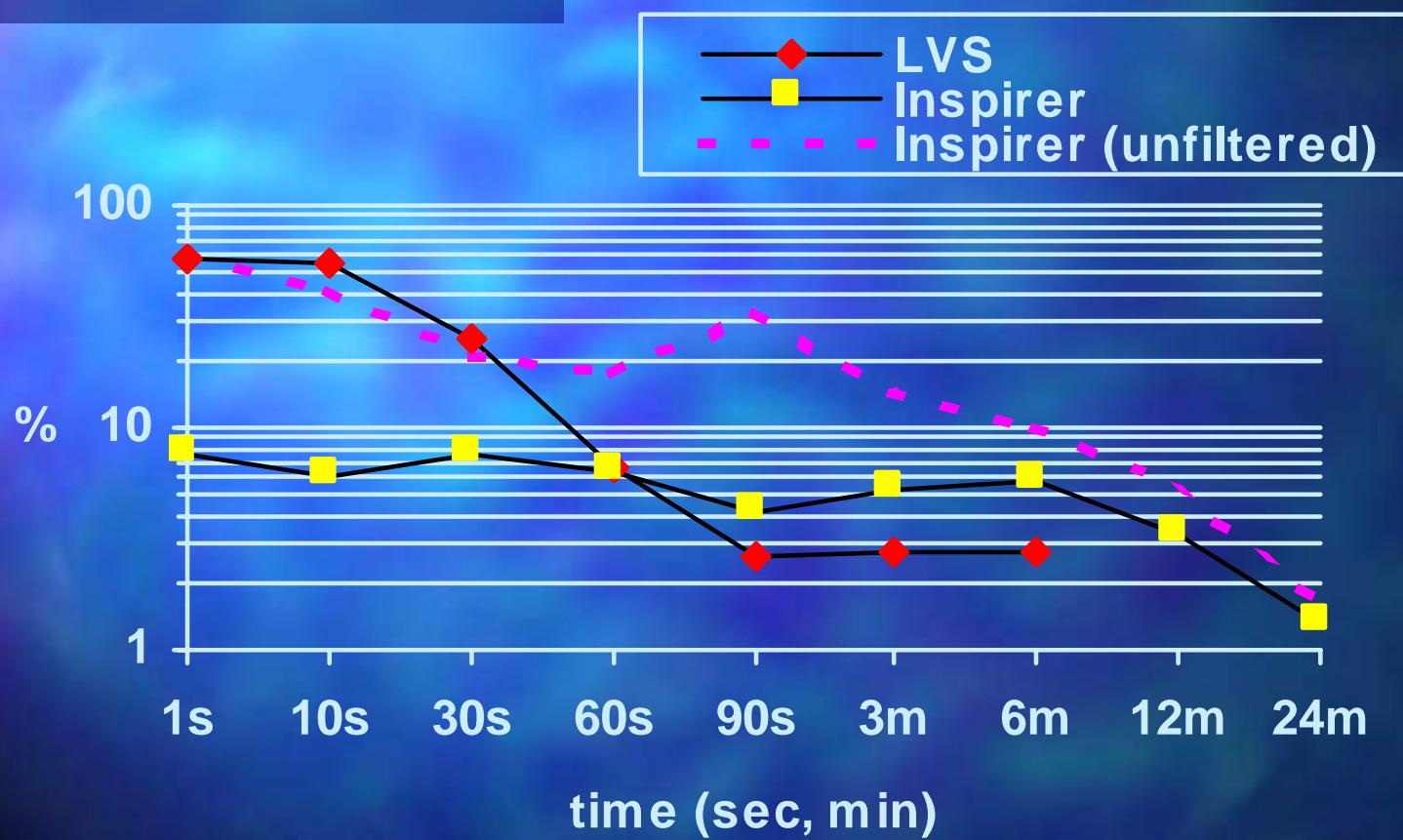
- $Illum(p)$  - is unknown luminance in some point P
- $lum(q)$  - is luminance at point Q
- $\Omega$  - integral spans over all surfaces in a scene
- $\alpha, \beta$  - are angles between normals in P, Q and PQ segment
- $r(p, q)$  - is Euclidean distance between P and Q
- $dA(q)$  - is differential area element at point Q

# Theoretical luminance values for cube

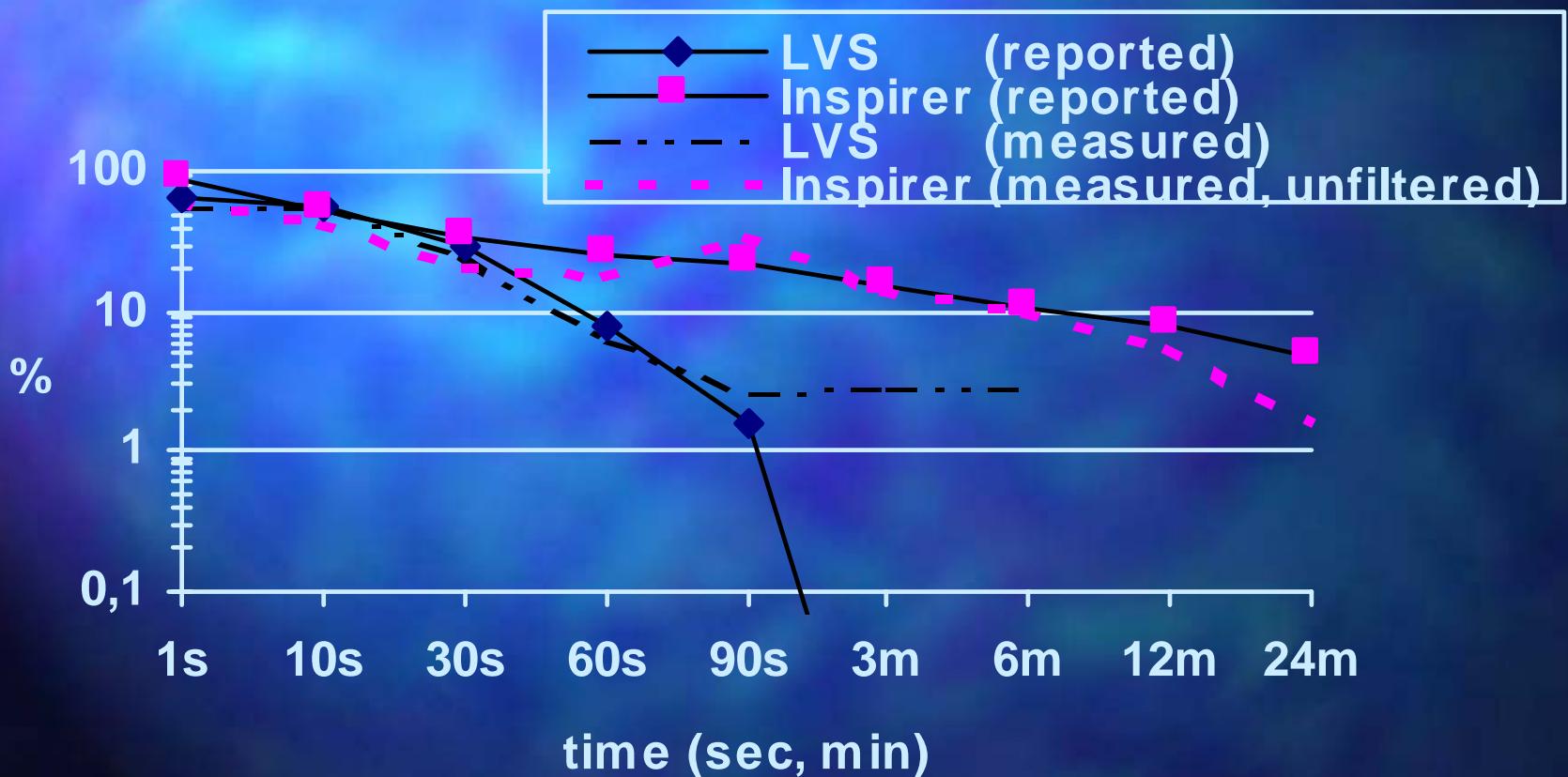


- A = 892.8 (cd/m<sup>2</sup>)
- B = 768.7 (cd/m<sup>2</sup>)
- C = 686.6 (cd/m<sup>2</sup>)
- D = 565.1 (cd/m<sup>2</sup>)
- E = 522.4 (cd/m<sup>2</sup>)
- F = 388.4 (cd/m<sup>2</sup>)
- A - 1/25
- B,C,D,F - 4/25
- E - 8/25

# CUBE: Measured error vs. time



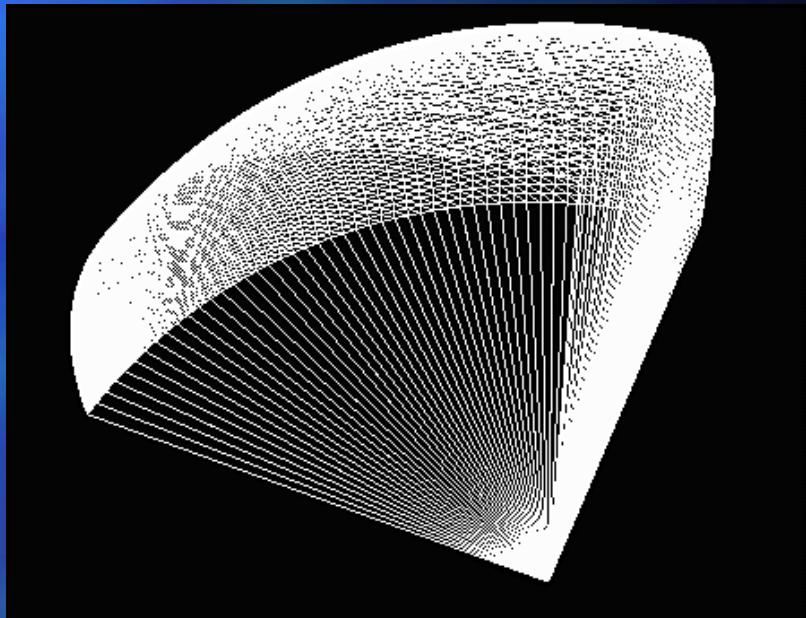
# CUBE: Reported error vs. time



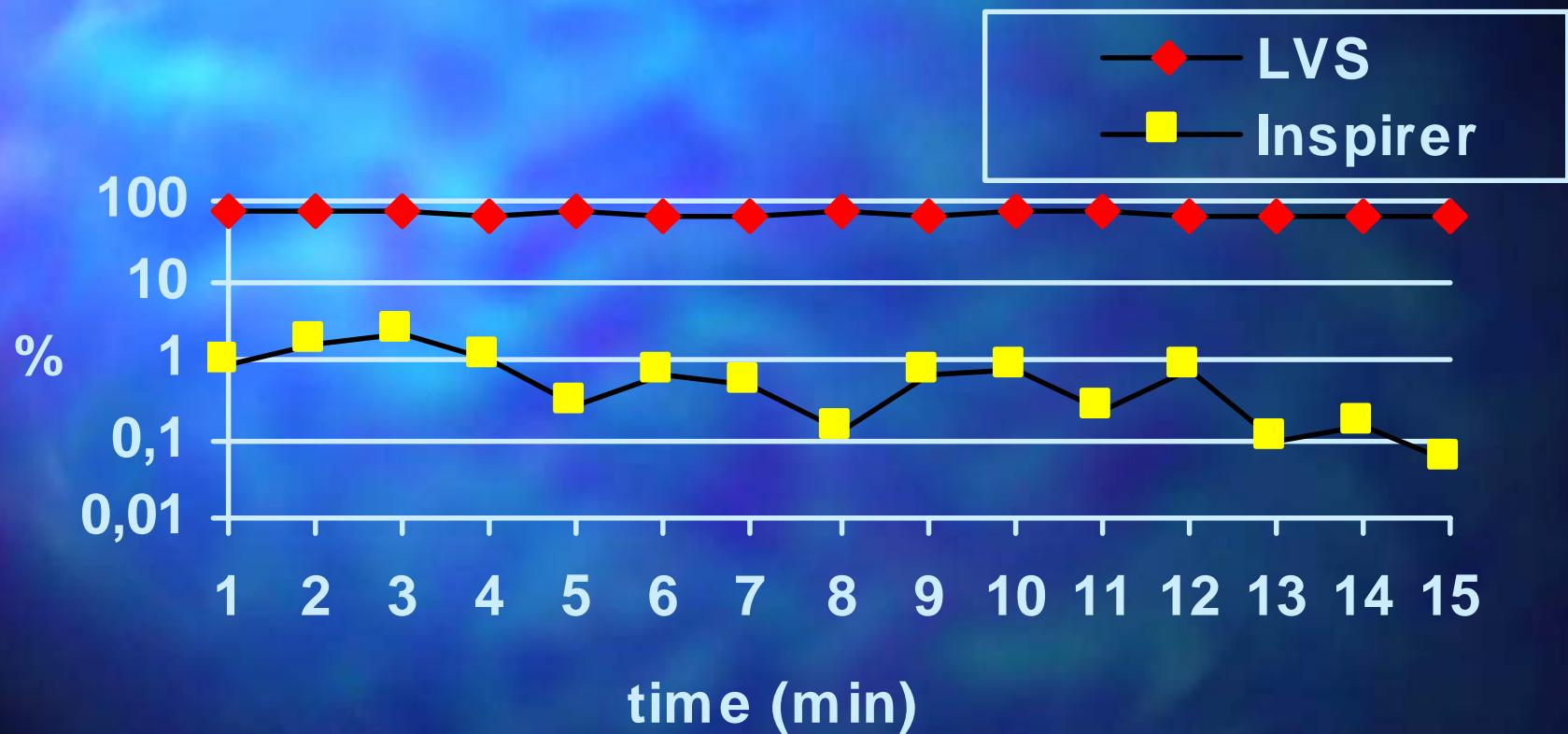
# SPHERE: diffuse-specular-diffuse energy transfer.

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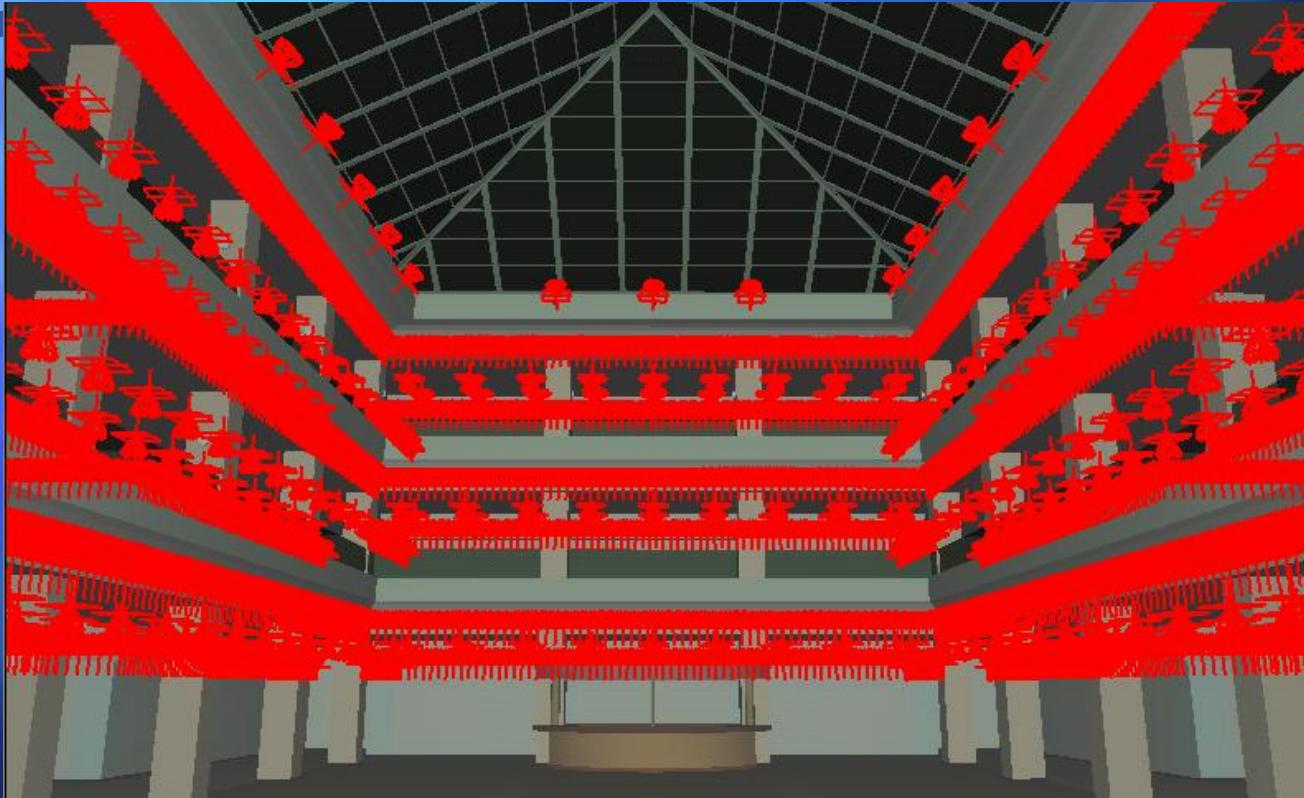
- a diffuse sphere
  - 3 mirror coordinate planes
  - exact ambient illuminance
  - form-factor is the same for all pairs of points
- 
- total illuminance in the center of sphere octant =  
1353.247 lux



# SPHERE: Simulation error vs. time



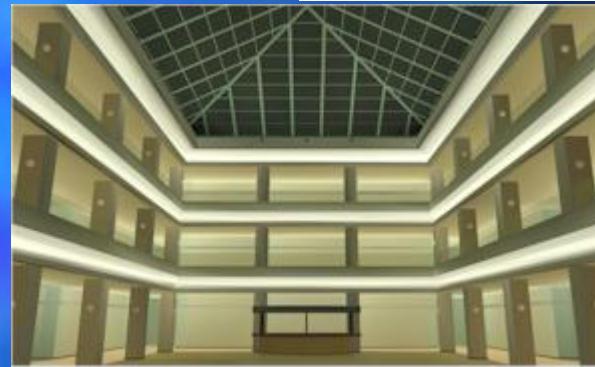
# TEST-E: Practical test



- about 10000 triangles
- 2626 luminaries for 3 types of photometric data



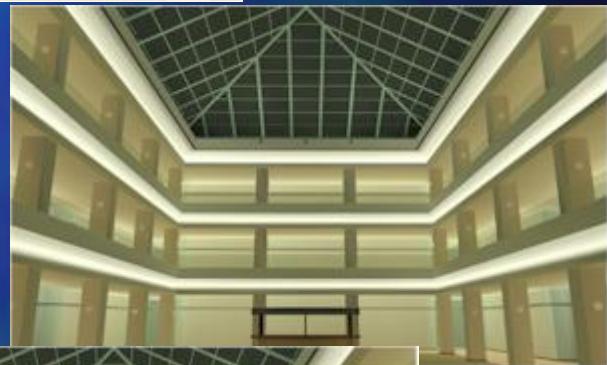
■ 1 min



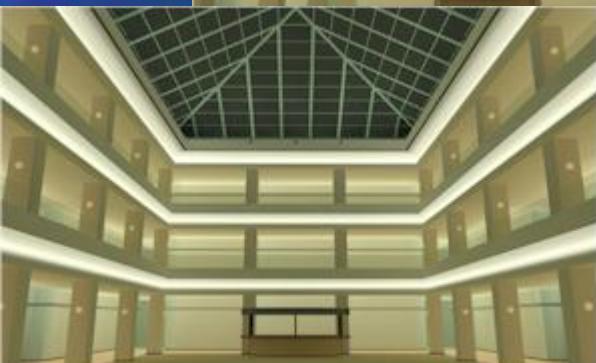
■ 8 min  
Inspirer



■ 64 min



■ 68 hours  
LVS



# NOTE

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- Inspirer reports progress in form of error estimation
- LVS produces progress reports in terms of initial energy. For example, 33.44% left means that 33.44% of initial energy still unshot. The actual accuracy level is unknown

# Note about shadows



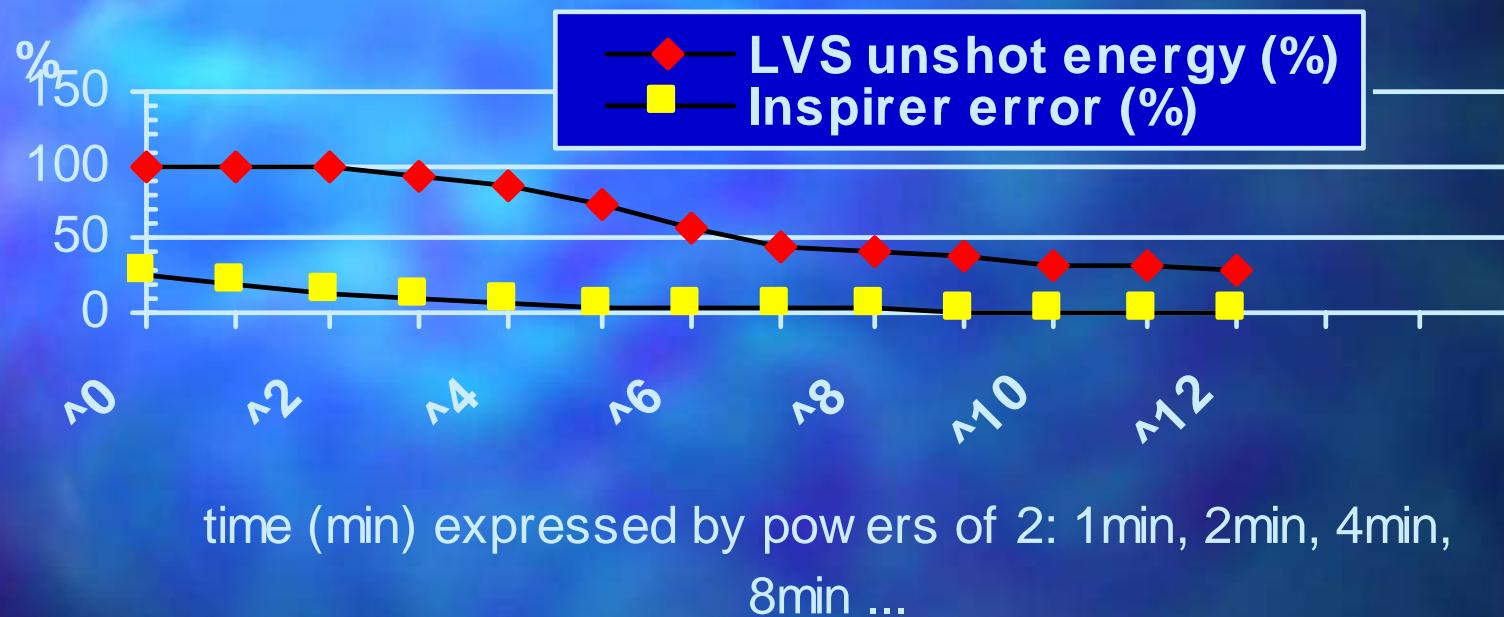
LVS



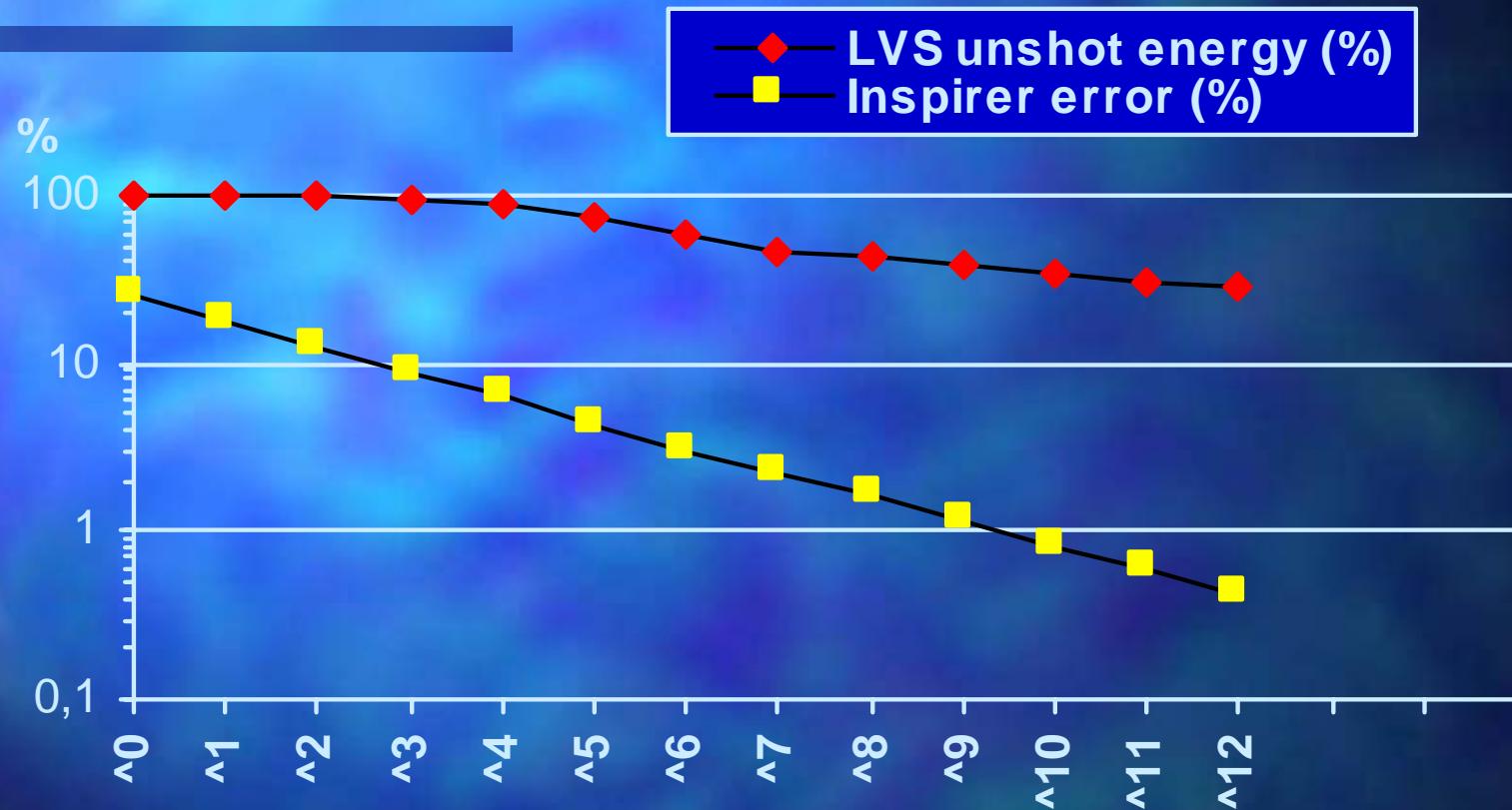
Inspirer

- incomplete calculation at this step for LVS

# Reported progress vs. time



# logarithmic scale



time (min) expressed by powers of 2: 1min, 2min, 4min, 8min...

- logarithm of error is changed linearly with logarithm of time

# Analysis of convergence speed

$$d(f, g) = \sqrt{\frac{1}{N} \sum_{i=1}^N (f_i - g_i)^2}$$

$$d_{rel}(f, g) = \frac{d(f, g)}{\|f\|}$$

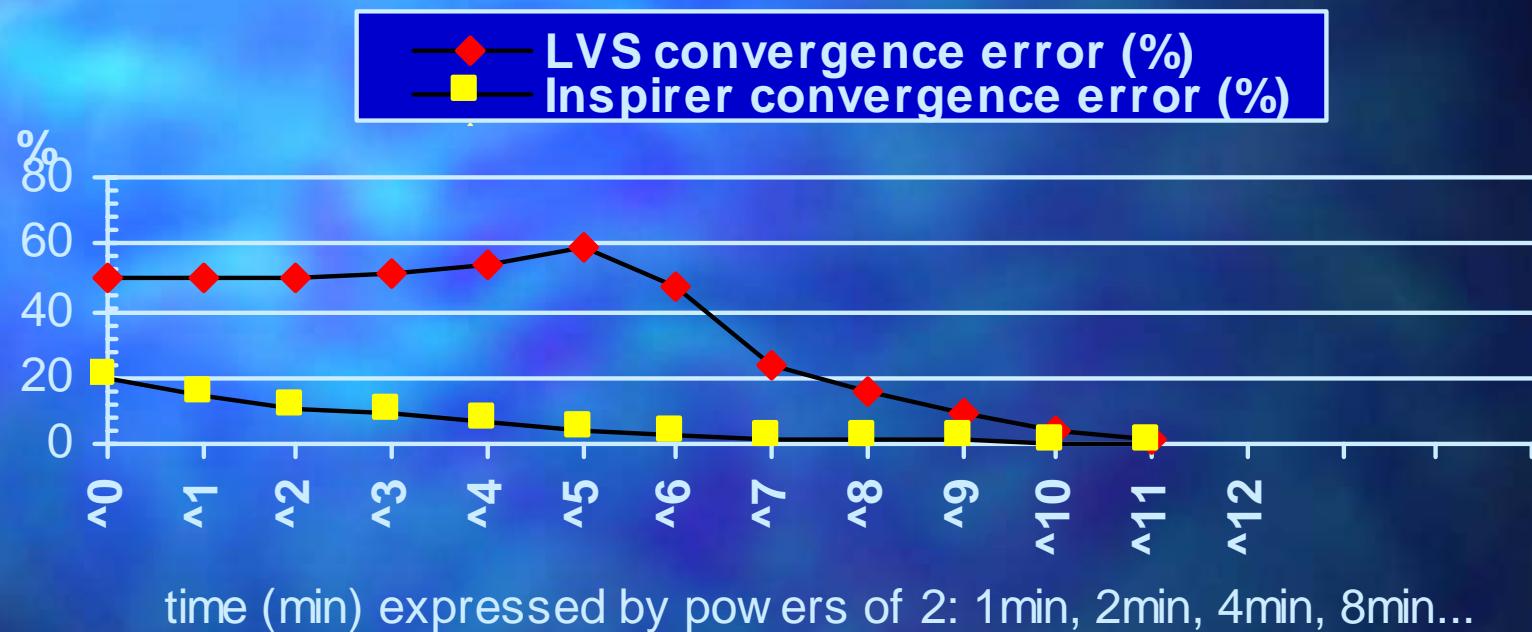
$N$ - number of pixels

$f$  - color component of reference image

$g$  - color component of compared with

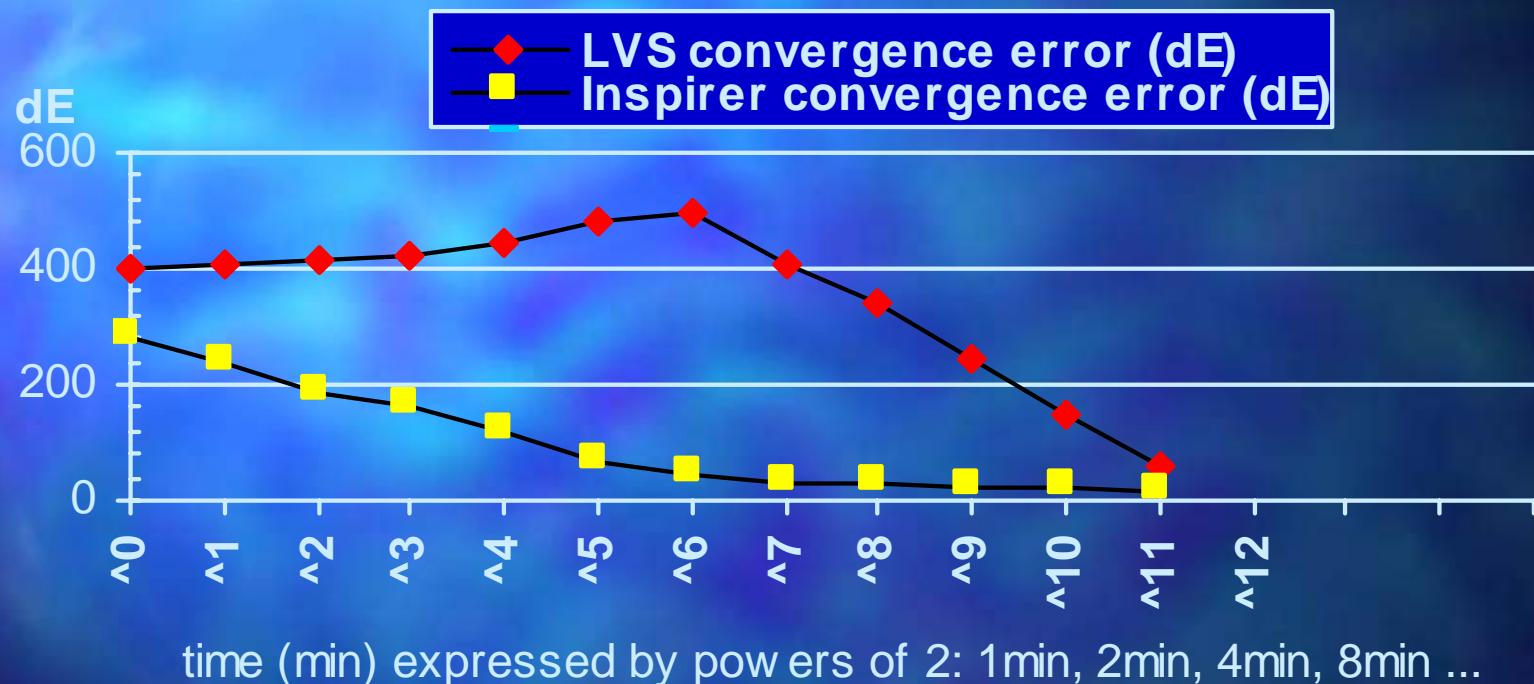
- This comparison is based on calculation of a distance (L2 in RGB) between intermediate images and some reference image
- $2^{12}$  minutes (about 68.5 hours)

# Convergence of images to reference one vs. time



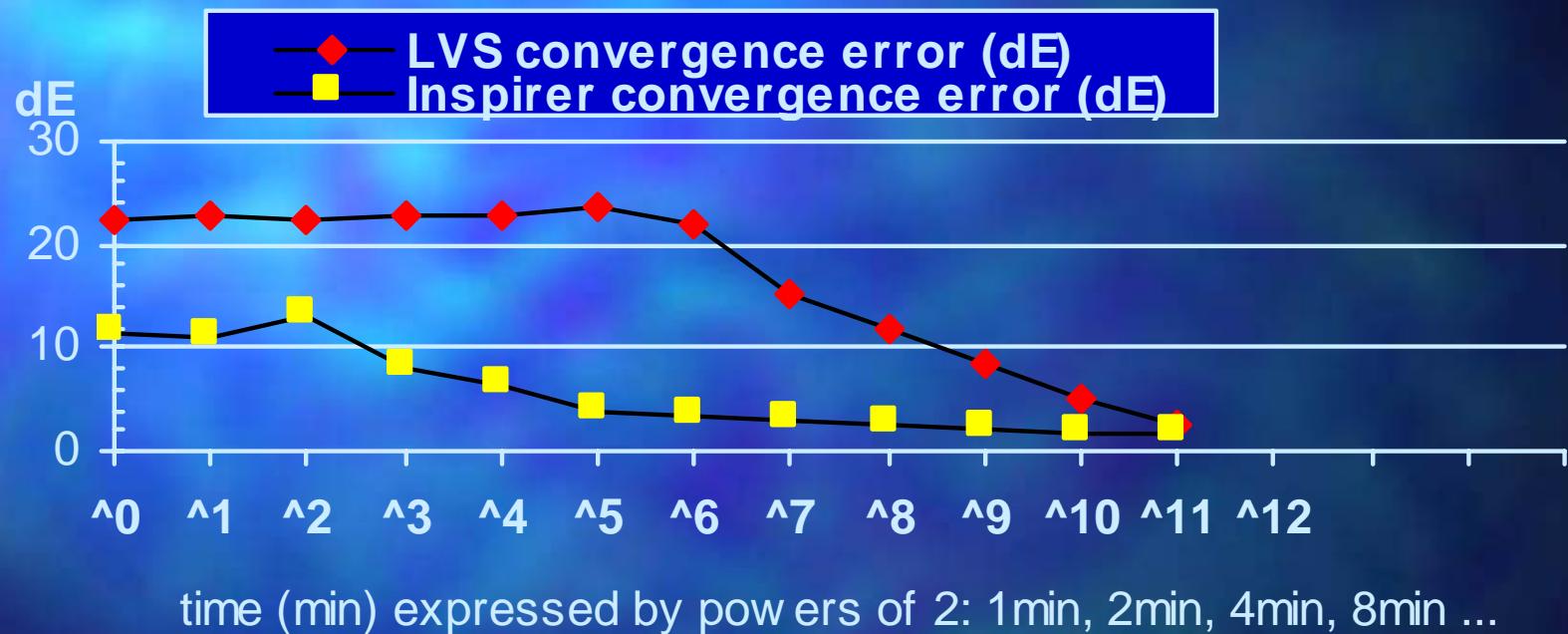
■ L2 metric in RGB

# Convergence of images to reference one vs. time



- Euclid metric in Lab CIE 1976

# Convergence of images to reference one vs. time



■ Euclid metric in Lab CIE 1995

International Conference Graphicon 1998,  
Moscow, Russia, <http://www.graphicon.ru/>